

Introduction to FEM

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FEM Convergence Requirements

Convergence Requirements for Finite Element Discretization

**Convergence: discrete (FEM) solution approaches
the analytical (math model) solution in some sense**

Convergence = Consistency + Stability

(Lax-Wendroff)

Further Breakdown of Convergence Requirements

- **Consistency**

Completeness *individual elements*

Compatibility *element patches*

- **Stability**

Rank Sufficiency *individual elements*

Positive Jacobian *individual elements*

The Variational Index m

Bar

$$\Pi[u] = \int_0^L \left(\frac{1}{2} u' E A u' - q u \right) dx$$

$$m = 1$$

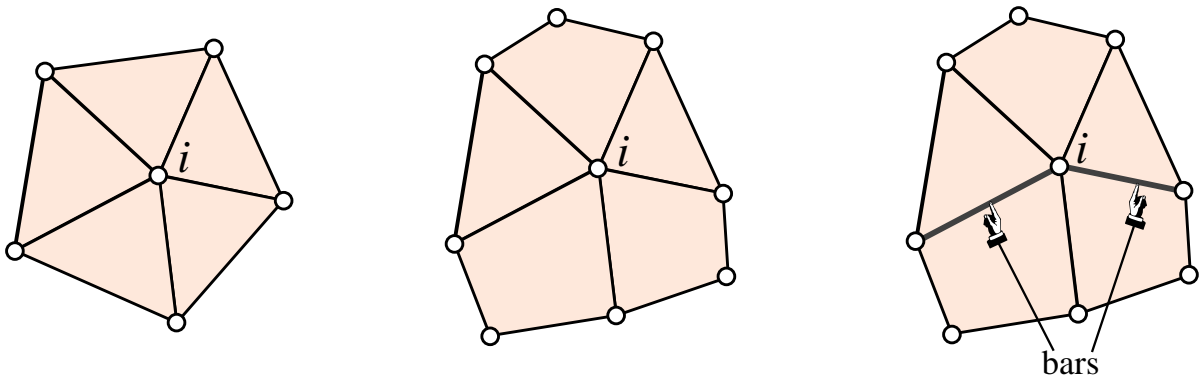
Beam

$$\Pi[v] = \int_0^L \left(\frac{1}{2} v'' E I v'' - q v \right) dx$$

$$m = 2$$

Element Patches

A **patch** is the set of all elements attached to a given node:



A finite element **patch trial function** is the union of shape functions activated by setting a degree of freedom at that node to unity, while all other freedoms are zero. A patch trial function "propagates" only over the patch, and is zero beyond it.

Completeness & Compatibility in Terms of m

Completeness

The *element shape functions* must represent exactly all polynomial terms of order $\leq m$ in the Cartesian coordinates. A set of shape functions that satisfies this condition is called m -complete

Compatibility

The *patch trial functions* must be $C^{(m-1)}$ continuous between elements, and C^m piecewise differentiable inside each element

Plane Stress: $m = 1$ in Two Dimensions

Completeness

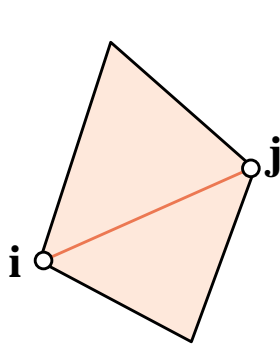
The *element shape functions* must represent exactly all polynomial terms of order ≤ 1 in the Cartesian coordinates. That means any *linear polynomial* in x, y with a *constant* as special case

Compatibility

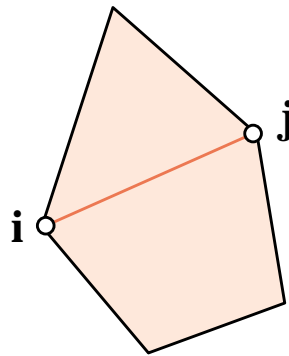
The *patch trial functions* must be C^0 continuous between elements, and C^1 piecewise differentiable inside each element

Interelement Continuity is the Toughest to Meet

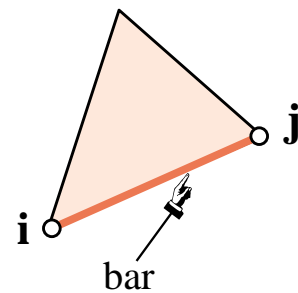
Simplification: for *matching meshes* (defined in Notes) it is sufficient to check a *pair of adjacent elements*:



Two 3-node linear triangles



One 3-node linear triangle and one 4-node bilinear quad

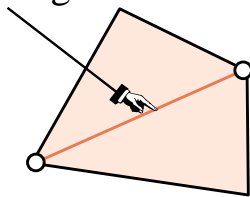


One 3-node linear triangle and one 2-node bar

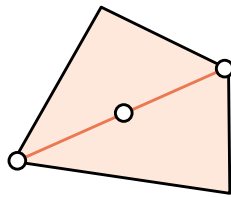
Side Continuity Check for Plane Stress Elements with Polynomial Shape Functions in Natural Coordinates

Let k be the number of nodes on a side:

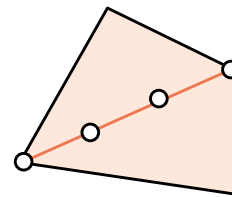
side being checked



$k = 2$



$k = 3$



$k = 4$

The variation of each element shape function along the side must be of polynomial order $k - 1$

If *more*, continuity is violated

If *less*, nodal configuration is wrong (too many nodes)

Stability

Rank Sufficiency

The discrete model must possess the same solution uniqueness attributes of the mathematical model

For displacement finite elements:

the rigid body modes (RBMs) must be preserved

no zero-energy modes other than RBMs

Can be tested by the **rank** of the stiffness matrix

Positive Jacobian Determinant

The determinant of the Jacobian matrix that relates Cartesian and natural coordinates must be everywhere *positive* within the element

Rank Sufficiency

The element stiffness matrix must not possess any zero-energy kinematic modes other than *rigid body modes*

This can be checked by verifying that the element stiffness matrix has the *proper rank*

A stiffness matrix that has proper rank is called *rank sufficient*

Rank Sufficiency for Numerically Integrated Finite Elements

General case

rank deficiency $d = (n_F - n_R) - r$

rank of \mathbf{K} $r = \min(n_F - n_R, n_E n_G)$

Plane Stress, n nodes

$$n_F = 2n \quad n_R = 3 \quad n_E = 3$$

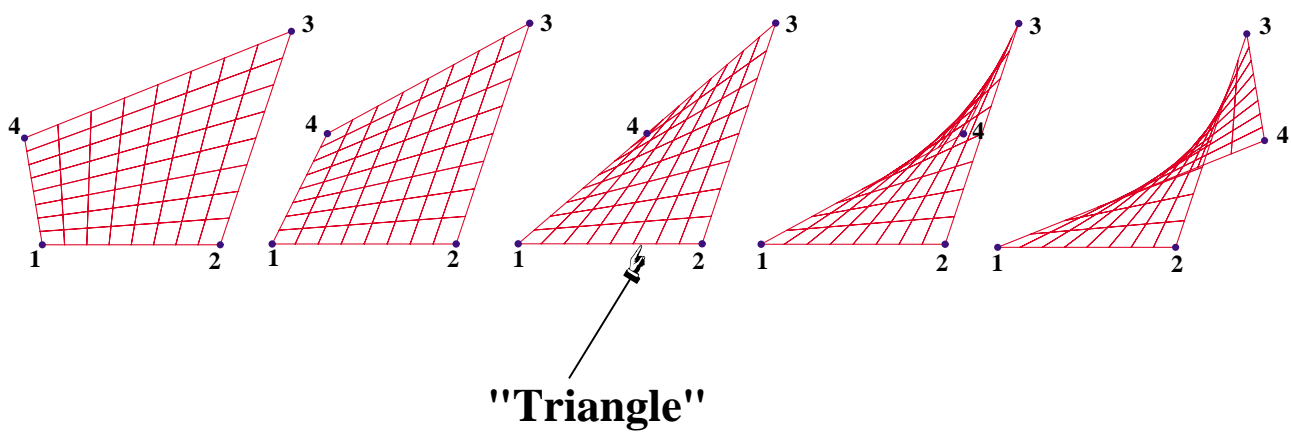
Rank Sufficiency for Some Plane Stress iso-P Elements

Element	n	n_F	$n_F - 3$	Min n_G	Recommended rule
3-node triangle	3	6	3	1	centroid*
6-node triangle	6	12	9	3	3-midpoint rule*
10-node triangle	10	20	17	6	7-point rule*
4-node quadrilateral	4	8	5	2	2 x 2
8-node quadrilateral	8	16	13	5	3 x 3
9-node quadrilateral	9	18	15	5	3 x 3
16-node quadrilateral	16	32	29	10	4 x 4

* Gauss rules for triangles are introduced in Chapter 24.

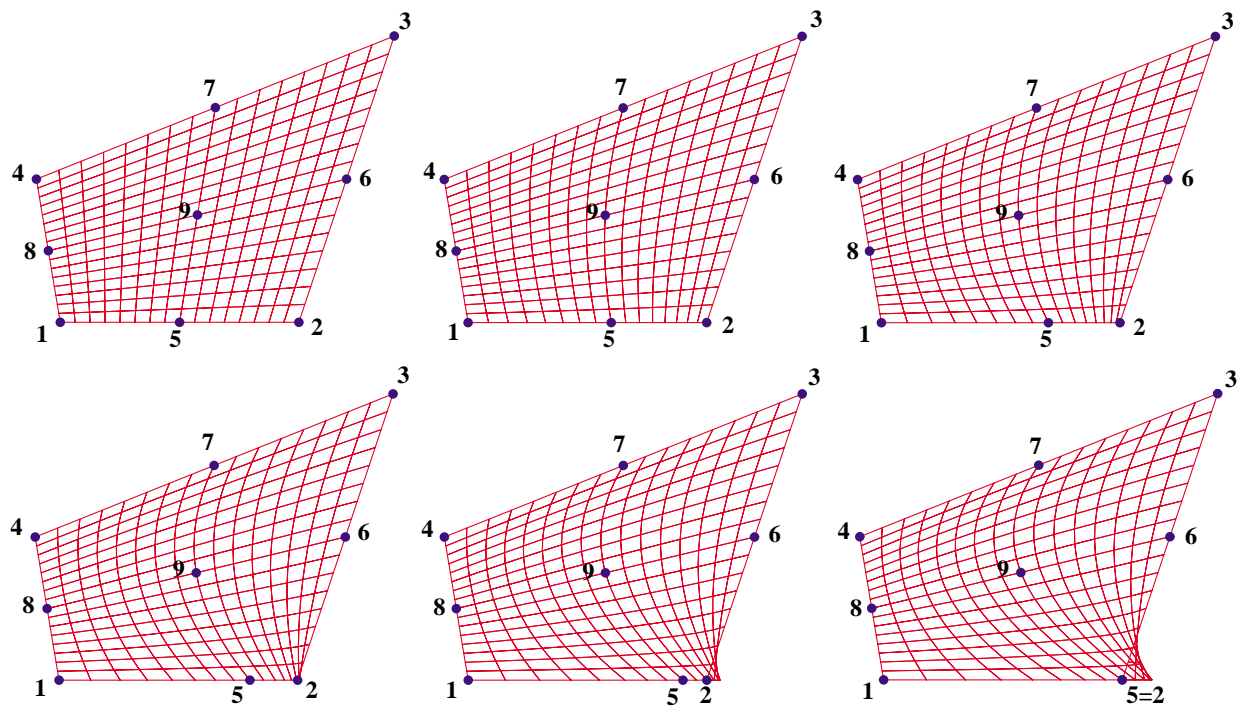
Positive Jacobian Requirement

Displacing a Corner Node of 4-Node Quad



Positive Jacobian (cont'd)

Displacing a Midside Node of 9-Node Quad



Positive Jacobian (cont'd)

Displacing Midside Nodes of 6-Node Equilateral Triangle

